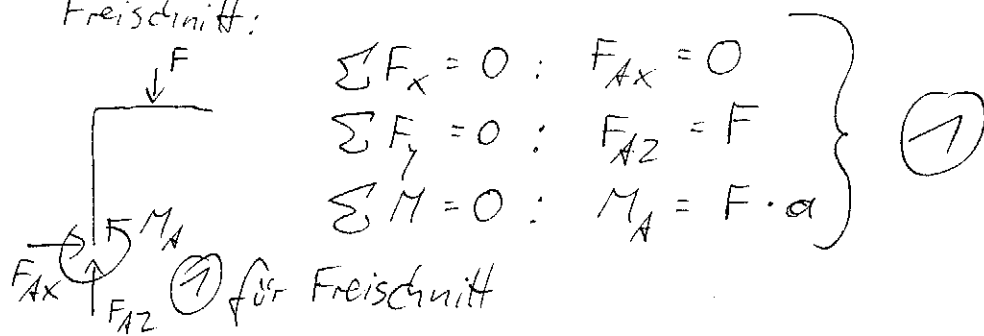


1

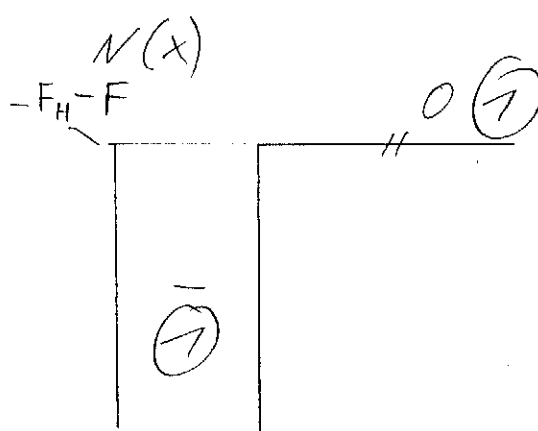
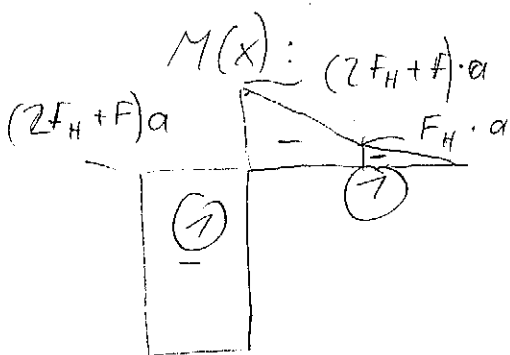
a) Freischnitt:



$$\left. \begin{aligned} \sum F_x = 0 &: F_{Ax} = 0 \\ \sum F_y = 0 &: F_{Az} = F \\ \sum M = 0 &: M_A = F \cdot a \end{aligned} \right\} \textcircled{1}$$

b) für Hilfskraft

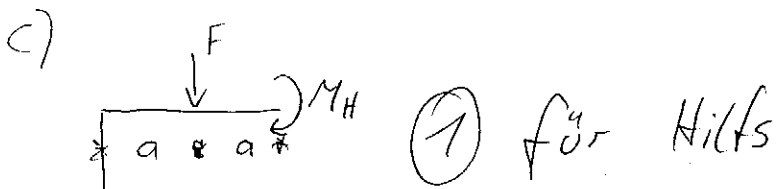
$$W = \frac{1}{2EA} \int_0^L N^2(x) dx + \frac{1}{2EI} \int_0^L M^2(x) dx \quad \textcircled{1} \text{ für } N(x) \text{ \& } M(x)$$



$$\begin{aligned} W = \frac{1}{2EA} 3a (F_H + F)^2 &+ \frac{1}{2EI} 3a \cdot [(2F_H + F) \cdot a]^2 \\ &+ \frac{1}{2EI} a \frac{1}{6} \left(2[(2F_H + F) \cdot a]^2 + 2[F_H \cdot a]^2 \right) \\ &+ 2(2F_H + F) \cdot a \cdot F_H \cdot a \\ &+ \frac{1}{2EI} a \frac{1}{3} (F_H \cdot a)^2 \quad \textcircled{2} \end{aligned}$$

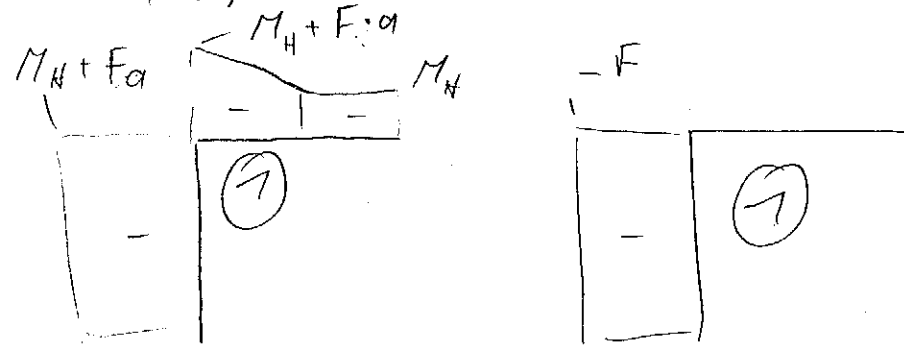
$$\delta = \frac{\partial W}{\partial F_H} \Big|_{F_H=0} = \frac{3aF}{EA} + \frac{4}{6} \frac{a^3 F}{EI} \quad \begin{matrix} \textcircled{1} \text{ für Ableitung} \\ \textcircled{1} \text{ für } F_H=0 \end{matrix}$$

$$\Rightarrow F = \frac{5}{\frac{3a}{EA} + \frac{4}{6} \frac{a^3}{EI}} \quad \textcircled{1}$$



$$W = \frac{1}{2EA} \int_0^L N^2(x) dx + \frac{1}{2EI} \int_0^L M^2(x) dx$$

$M(x)$:



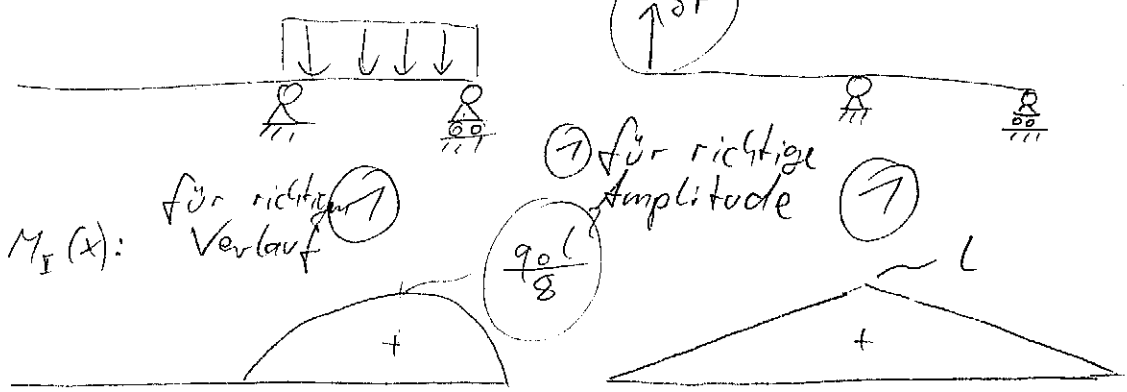
$$\begin{aligned}
 W &= \frac{1}{2EA} 3a F^2 + \frac{1}{2EI} 3a (M_H + F \cdot a)^2 \\
 &\quad + \frac{1}{2EI} a \frac{1}{6} \left(2(M_H + F \cdot a)^2 + 2(M_H)^2 \right. \\
 &\quad \quad \left. + 2(M_H + F \cdot a) M_H \right) \\
 &\quad + \frac{1}{2EI} a M_H^2 \quad \text{①}
 \end{aligned}$$

$$\begin{aligned}
 \psi &= \frac{\partial W}{\partial M_H} \Big|_{M_H=0} = \frac{21 F a^2}{6EI} \quad \text{①} \\
 &= \frac{7 F a^2}{3EI}
 \end{aligned}$$

2

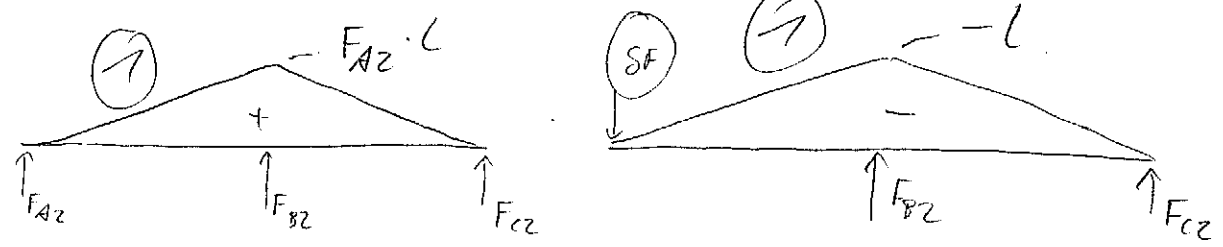
- a) 4 Lagerkräfte
 3 Gleichungen
 \Rightarrow 1-fach statisch unbestimmt

b) Teilsystem I: \rightarrow für δF an richtiger Stelle



$$S_I = \frac{1}{EI} \cdot L \cdot \frac{1}{3} \cdot \frac{q_0 L^2}{8} \cdot L = \frac{q_0 L^4}{EI \cdot 24}$$

Teilsystem II: \rightarrow für δF an richtiger Stelle

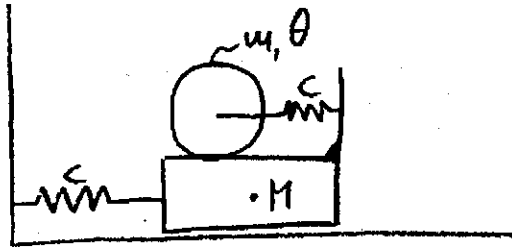


$$S_{II} = -\frac{1}{EI} \cdot 2L \cdot \frac{1}{3} \cdot F_{A2} \cdot L^2$$

Superposition:

$$S_I - S_{II} = 0 \Rightarrow F_{A2} = -\frac{q_0 L}{16}$$

Aufgabe 3



1. Freiheitsgrade

$$f = 2 - k = 6 - 4 = 2$$

2 Körper
3 Freiheitsgrade

Bedingungen:

$$y_1 = 0$$

$$x_1 = x_s - r\dot{\varphi} = x_w$$

$$p_1 = q_1$$

$$y_2 = 0$$

$$x_2 = q_2 = x_s$$

$$p_2 = 0$$



2) Aufstellen der Energieen und generalisierte Kräfte

$$E_{kin} = \frac{1}{2} M \dot{x}_s^2 + \frac{1}{2} m \dot{x}_w^2 + \frac{1}{2} \Theta_s \dot{\varphi}^2$$

$$= \frac{1}{2} M \dot{x}_s^2 + \frac{1}{2} m (\dot{x}_s - r\dot{\varphi})^2 + \frac{1}{2} \Theta_s \dot{\varphi}^2$$



$$U = \frac{1}{2} c (\Delta x_1)^2 + \frac{1}{2} c (\Delta x_2)^2 = \frac{1}{2} c r^2 \varphi^2 + \frac{1}{2} c x_s^2$$



$$\Rightarrow L = \frac{1}{2} M \dot{x}_s^2 + \frac{1}{2} m (\dot{x}_s - r\dot{\varphi})^2 + \frac{1}{2} \Theta_s \dot{\varphi}^2 - \frac{1}{2} c r^2 \varphi^2 - \frac{1}{2} c x_s^2$$

~~$Q_i = 0$~~

$$Q_\varphi = 0$$

$$Q_x = F(t)$$



3) Ableitungen der Lagrange'schen Gleichungen

Koordinate x_S

$$i) \frac{\partial L}{\partial \dot{x}_S} = M \dot{x}_S + m (\dot{x}_S - r \dot{\varphi})$$

$$ii) \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}_S} \right) = M \ddot{x}_S + m \ddot{x}_S - r m \ddot{\varphi} = (M+m) \ddot{x}_S - r m \ddot{\varphi} \quad (\rightarrow)$$

$$iii) \frac{\partial L}{\partial x_S} = -c x_S \quad (\rightarrow)$$

Koordinate φ

$$i) \frac{\partial L}{\partial \dot{\varphi}} = m (\dot{x}_S - r \dot{\varphi}) (-r) + \Theta_S \dot{\varphi}$$

$$ii) \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\varphi}} \right) = -m r \ddot{x}_S + m r^2 \ddot{\varphi} + \Theta_S \ddot{\varphi} \quad (\rightarrow)$$

$$iii) \frac{\partial L}{\partial \varphi} = -c r \varphi^2 \quad (\rightarrow)$$

4) Einsetzen in Lagrange Gleichungen

Koordinate x_S

$$(M+m) \ddot{x}_S - r m \ddot{\varphi} + c x_S = \cancel{0} F(t) \quad (\rightarrow)$$

Koordinate φ

$$-m r \ddot{x}_S + m r^2 \ddot{\varphi} + \Theta_S \ddot{\varphi} + c r \varphi^2 = 0 \quad (\rightarrow)$$