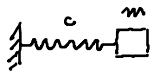


Vorlesung am 6.7.2018

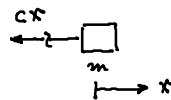
- Wiederholung: Schwingungsdgl. ohne Dämpfung
- Lösungsansatz mit exp-Funktion
- Eigenwerte
- Federkonstanten

• Schwingung mit Coulomb Dämpfung

Niederholungs



Freischnitt a



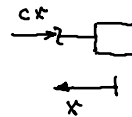
$$m \ddot{x} = -c x$$

$$\ddot{x} + \frac{c}{m} x = 0 \quad (1)$$

Eigenfrequenz $\omega = \sqrt{\frac{c}{m}} = \frac{2\pi}{T}$ ← Schwingungsdauer

$$T = 2\pi \sqrt{\frac{m}{c}}$$

Freischnitt



$$m \ddot{x} = -c x$$

Lösung der Dgl. (1)

$$\ddot{x} + \omega^2 x = 0, \text{ gesucht } x(t)$$

1) Fußpunktverfahren

$$x(t) = A \sin(\omega t) + B \cos(\omega t)$$

$$\dot{x}(t) = \omega [A \cos(\omega t) - B \sin(\omega t)]$$

AB: 1) $x(t=0) = x_0 = A \cdot 0 + B \cdot 1 \Rightarrow B = x_0$

2) $\dot{x}(t=0) = v_0 = \omega [A \cdot 1 - B \cdot 0] \Rightarrow A = \frac{v_0}{\omega}$

$$\Rightarrow x(t) = \frac{v_0}{\omega} \sin(\omega t) + x_0 \cos(\omega t) \quad \text{harmonische Schwingung}$$

2) Exponentialansatz

$$x(t) = A \exp(\beta t)$$

$$\dot{x}(t) = \beta A \exp(\beta t)$$

$$\ddot{x}(t) = \beta^2 A \exp(\beta t) = \beta^2 x(t)$$

$m(1): [\beta^2 + \omega^2] x(t) = 0$

$$\Rightarrow \beta^2 = -\omega^2 \Rightarrow \beta = \pm i \omega \Rightarrow x(t) = A_1 \exp(i \omega t) + A_2 \exp(-i \omega t)$$

$$A_1 = A_1^1 + i A_1^2$$

$$A_2 = A_2^1 + i A_2^2$$

$$= (A_1^1 + A_2^1) \cos(\omega t) +$$

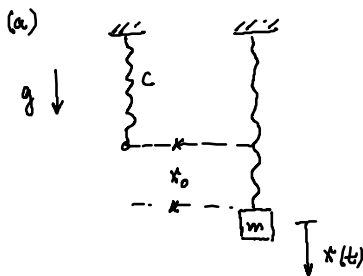
$$+ i (A_1^2 - A_2^2) \sin(\omega t)$$

$$\stackrel{\text{B}}{\cong} A$$

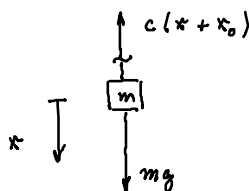
$$A_1^2 = -A_2^2, A_1^1 = A_2^1$$

Euler $\exp(i \alpha) = \cos \alpha + i \sin \alpha$
 $\exp(-i \alpha) = \cos \alpha - i \sin \alpha$

Dre Dgl. des harmonischen 1D-Schwingers in "Verkleidung"



Freischnitt



Gleichung:

$$m \ddot{x} = -c(x+x_0) + mg$$

Statische Ruhelage $x_{st} \Rightarrow \ddot{x}_{st} = 0$

$$0 = -c(x_{st} + x_0) + mg$$

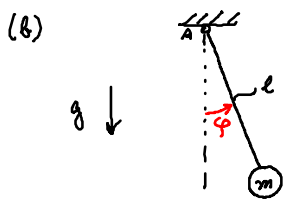
$$x_{st} = \frac{mg}{c} - x_0$$

Def.: $\tilde{x} = x - x_{st} \Rightarrow \ddot{\tilde{x}} = \ddot{x}$

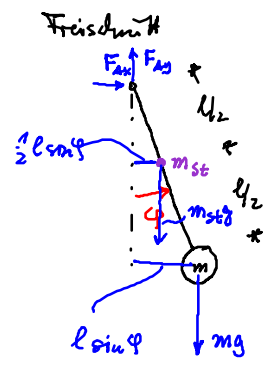
$$\Rightarrow m \ddot{\tilde{x}} = -c(\tilde{x} + x_{st} + x_0) + mg =$$

$$= -c \tilde{x} - \cancel{mg} + \cancel{mg}$$

$$\Rightarrow \ddot{\tilde{x}} + \frac{c}{m} \tilde{x} = 0$$



- (1) Faden masselos
- (2) Stange mit Masse m_{st}



Drehsatz

$$+ \Theta^{(A)} \ddot{\varphi} = -mgl \sin \varphi$$

$$(1) \Theta^{(A)} = ml^2$$

$$(2) \Theta^{(A)} = ml^2 + \frac{m_{st}}{3} l^2$$

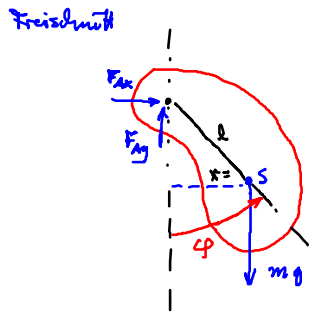
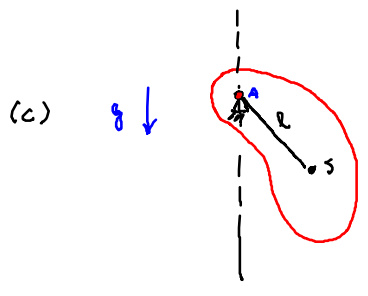
$$(1): \ddot{\varphi} m l^2 = -mgl \sin \varphi$$

$$\Rightarrow \ddot{\varphi} + \frac{g}{l} \sin \varphi = 0$$

$\omega^2 \sin \varphi \approx \varphi$ für kleine Auslenkungen

$$\ddot{\varphi} + \omega^2 \varphi = 0$$

$$(2) \left(m + \frac{m_{st}}{3}\right) l^2 \ddot{\varphi} = -mgl \sin \varphi - m_{st} g \frac{l}{2} \sin \varphi$$



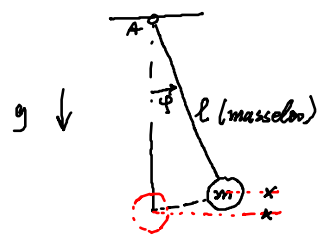
Drehsatz

$$+ \Theta^{(A)} \ddot{\varphi} = -mgl \sin \varphi$$

$$\ddot{\varphi} + \frac{mgl}{\Theta^{(A)}} \sin \varphi = 0$$

$= \omega^2 \approx \varphi$

Energiesatz am Beispiel des Fadenpendels



$$\omega^2 = \frac{g}{l}$$

Energiesatz:

$$E^{kin}(t) + E^{pot}(t) = E^{kin}(0) + E^{pot}(0)$$

$$E^{kin}(t) = \frac{m}{2} (v_\varphi)^2 = \frac{m}{2} (l \dot{\varphi}(t))^2$$

$$E^{pot}(t) = mgl(l - l \cos \varphi) = mgl(1 - \cos \varphi(t)) \approx mgl \frac{\varphi^2}{2}$$

$\cos \varphi \approx 1 - \frac{\varphi^2}{2}$

$$E^{kin}(0) = 0$$

$$E^{pot}(0) = mgl \frac{\varphi_0^2}{2} = E_0$$

Lösung der Bewegung: $\varphi(t) = \varphi_0 \cos(\omega t)$

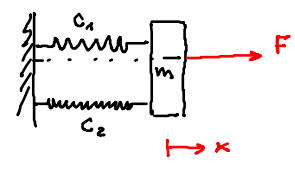
$$E^{kin}(t) = \frac{m l^2}{2} \dot{\varphi}^2(t) = \dots = \frac{E_0}{2} [1 - \cos(2\omega t)]$$

$$E^{pot}(t) = \frac{m l^2}{2} \varphi^2(t) = \dots = \frac{E_0}{2} [1 + \cos(2\omega t)]$$

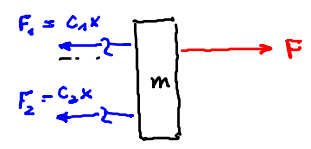
Energie schwanken doppelt so schnell

Ersatzschaltungen für mehrere Systemfedern

(a) Parallelschaltung



Freischnitt

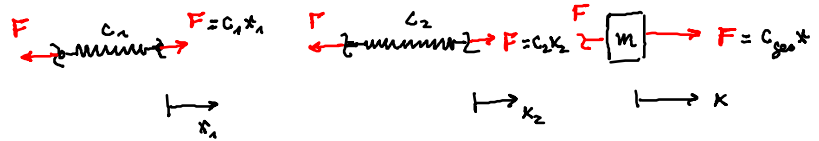
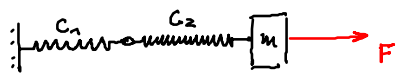


Wie groß ist die Ersatzspringkonstante c_{ges} als Fkt. von c_1 und c_2

$$F = F_1 + F_2$$

$$c_{ges} x = (c_1 + c_2) x \Rightarrow c_{ges} = c_1 + c_2$$

(b) Serienschaltung



$$x_1 + x_2 = x \Rightarrow \frac{F}{c_1} + \frac{F}{c_2} = \frac{F}{c}$$

$$\frac{1}{c} = \frac{1}{c_1} + \frac{1}{c_2}$$